3rd Lab Practice: Finding optimal paths using A\*

In this practice you would find the optimal path using A\*,

Add to the system previously developed the ability to manage terrain types, for example, water, sand, soil, forest, etc. An Example of the new map

|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O |
| 1 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 3 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4 |  | I |  |  |  |  | F |  |  |  |  |  |  |  |  |
| 5 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 7 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 8 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 9 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 10 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 11 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 12 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 13 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 14 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 15 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

|  |  |  |
| --- | --- | --- |
| Color | Means | Coded Value |
|  | Mountain | 0 |
|  | Land | 1 |
|  | Water | 2 |
|  | Sand | 3 |
|  | Forest | 4 |
|  |  |  |

Observe that the initial and final points can, be in any point of the map.

The coded used is:

|  |  |
| --- | --- |
| Value | Means |
| I | Initial point |
| F | Final point |

Also add the possibility to specify the cost of occupy a cell in accord to the terrain type. For example we can define two types of individual as follows:

|  |  |  |
| --- | --- | --- |
| Terrain | Cost movement | |
| Monkey | Octopus |
| Mountain | N/A | N/A |
| Earth | 2 | 2 |
| Water | 4 | 1 |
| Sand | 3 | N/A |
| Forest | 1 | 3 |

So, for the same map, taking account of the same initial point and the same final point, the best path founded for these two beings would be different.

Also consider that a being X is collocated inside the map, is able to memorize the labyrinth the knowledge of the map already visited and is able to see only one cell of distance (up, down, left and right). Initially the being inside doesn’t know all the map and discover it travelling, and discover only what he can see; however the position of the final point is known from the beginning. For example, the initial knowledge of the previous map is

|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O |
| 1 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 3 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4 |  | I |  |  |  |  | F |  |  |  |  |  |  |  |  |
| 5 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 6 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 7 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 8 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 9 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 10 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 11 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 12 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 13 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 14 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 15 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

In the map the open nodes are marked with O and the closed nodes are marked with X and between parentheses the total cost

In our example, the first evolution would be:

|  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
|  | A | B | C | D | E | F | G | H | I | J | K | L | M | N | O |
| 1 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 3 |  | O(7) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 4 | O(7) | I,X(5) | O(8) |  |  |  | F |  |  |  |  |  |  |  |  |
| 5 | O(9) | X(7) | O(12) |  |  |  |  |  |  |  |  |  |  |  |  |
| 6 |  | O(9) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 7 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 8 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 9 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 10 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 11 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 12 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 13 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 14 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 15 |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

Develop a system that:

1. Establish the initial and final point of the map
2. Solve automatically the labyrinth using A\*, having the possibility to specify optional goals and subgoals.
3. Show the actual discovered map
4. Show the actual solution tree generated
5. The system has to bring the option to show the optimal path discovered.